



Designing a Robot Chassis

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TOOLS:

- [Printer \(1\)](#)
- [Rotary tool with cut-off wheel \(1\)](#)
- [scale or vernier calipers \(1\)](#)



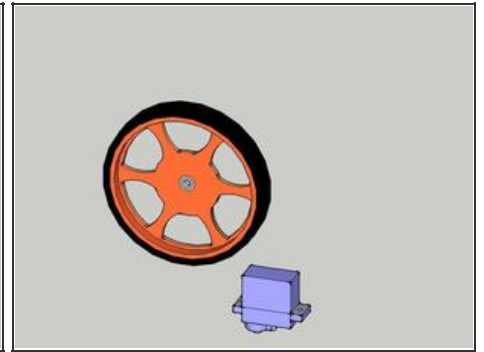
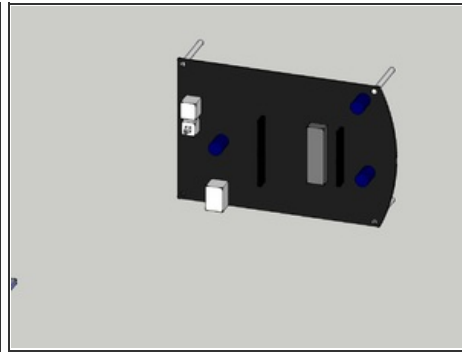
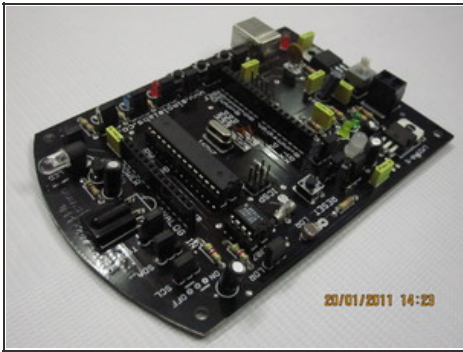
PARTS:

- [acrylic sheet 2mm \(1\)](#)
- [Glue \(1\)](#)

SUMMARY

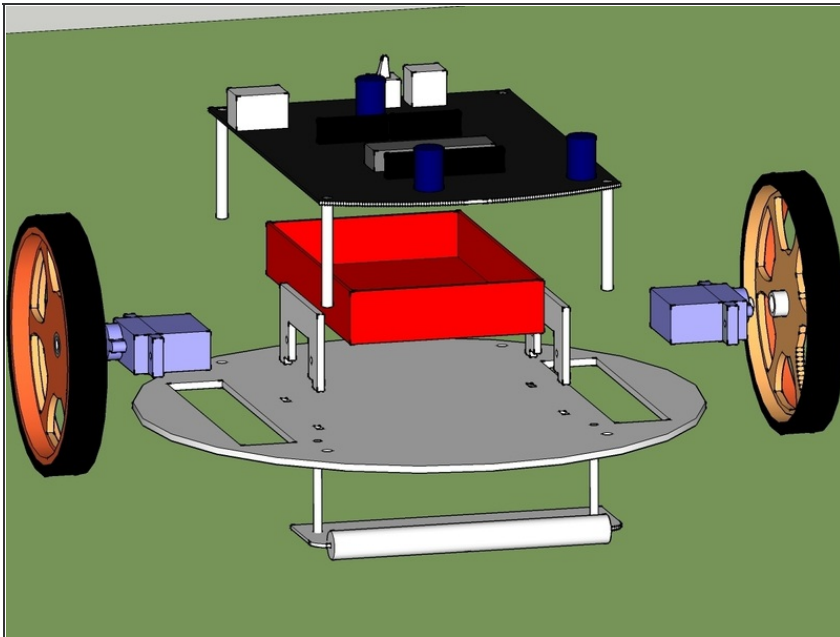
We will be using freely available tools like Google SketchUp to design and finally fabricate a chassis for a robot.

Step 1 — Create parts in SketchUp.



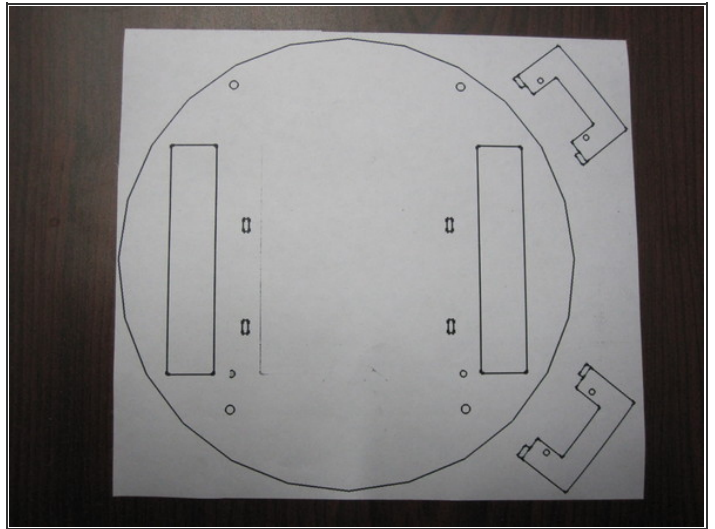
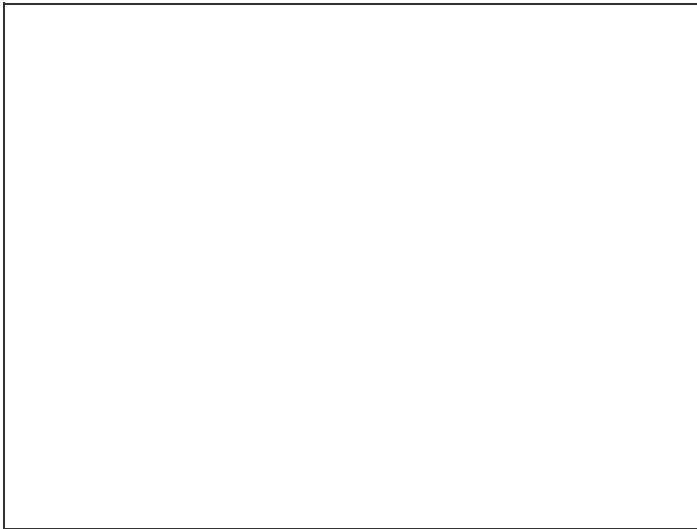
- Use a scale or, preferably, a vernier caliper to measure the parts you already have, then recreate them in SketchUp.
- I used an Arduino clone (induinoX).
- When creating the board in SketchUp create only the big parts that stick out to save time.
- Create the chassis in the shape you prefer.
- You can create slots by subtracting the slot's shape from the chassis.

Step 2 — Google SketchUp assembly



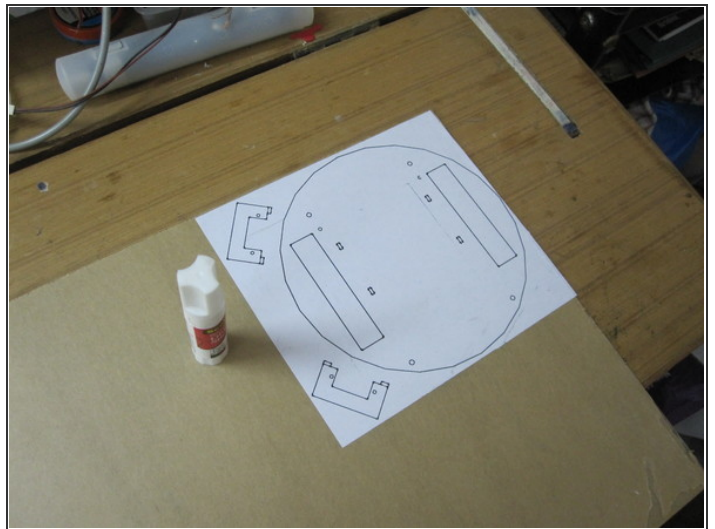
- Assemble the parts in Google SketchUp.
- See if all the parts fit together.

Step 3 — Print the chassis



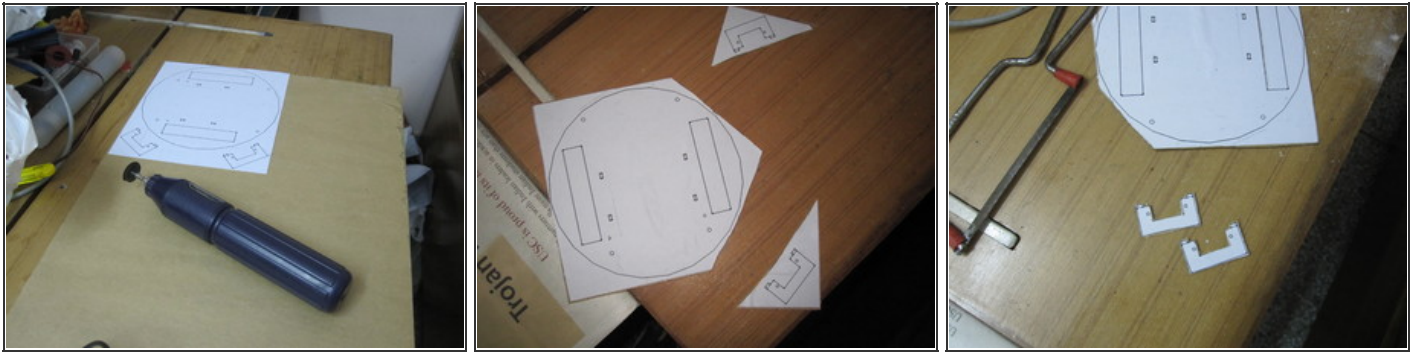
- Print the outline of the parts for the chassis.
- Use the option that keeps the size of the printout to the actual size.
- Check the measurements after printing to be double-sure.

Step 4 — Apply the template



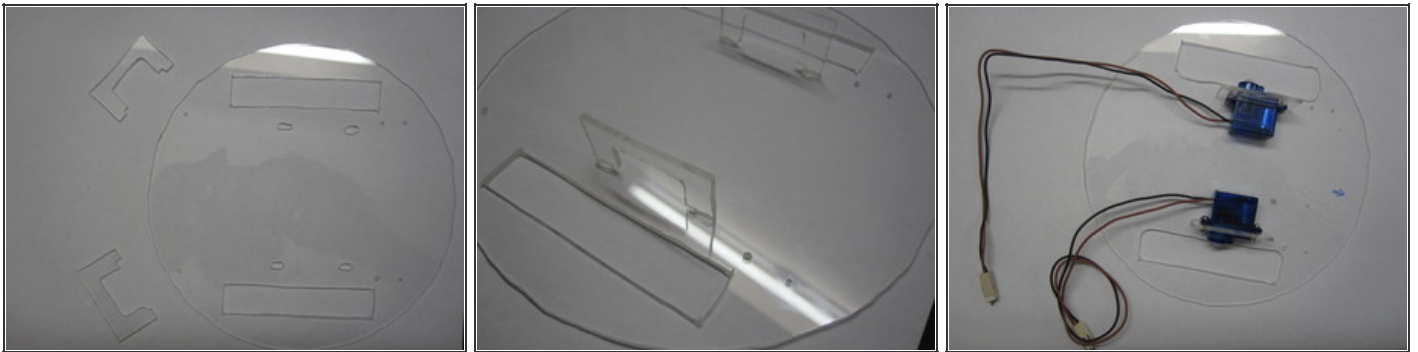
- Paste the printout on the material you want to cut the chassis from.
- I used 2mm acrylic sheet.
- Take care when pasting the printout that there are no creases in it.

Step 5 — Cut out the shapes



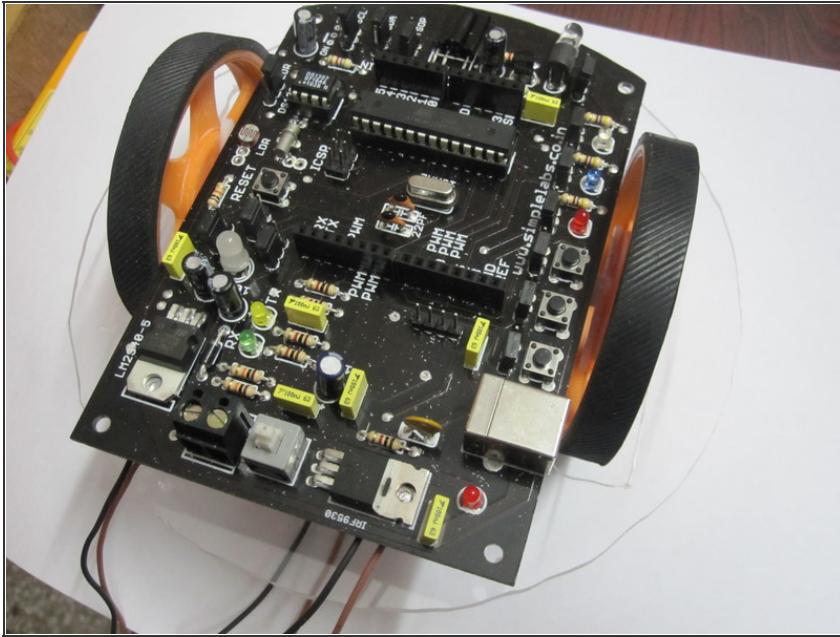
- Use a rotary tool or a hacksaw to cut out your shapes.

Step 6 — Glue the parts



- Use super glue to stick the parts together.
- I made the parts like jigsaw pieces so they meshed together to give more strength.
- Screw in the other parts like motors, caster wheels, etc.

Step 7



- Finished chassis with the InduinoX board.

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